Jerry Olds  
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IE-4378-001  
10/29/2019

Path Planning needed for Competition



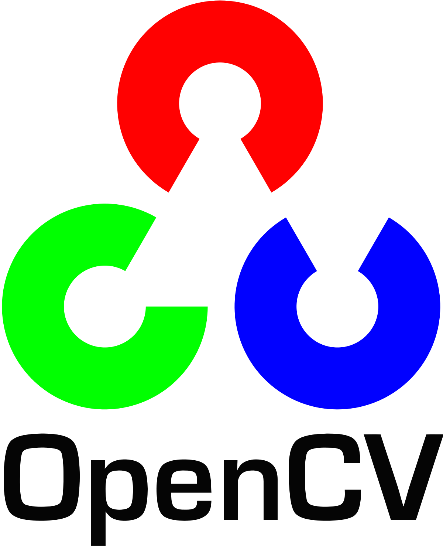
N910 Skype Web Camera Wide Angle  
 (Used for lane detection)



Ouster OS-1 Performance Lidar Sensor  
 (Used for obstacle detection)



Robot Operating System package BreezySlam for map building and path generation



OpenCV to detect lanes